

Low-Distortion Signal Generation for Analog/Mixed-Signal IC Testing Using Digital ATE Output Pin and BOST

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Research Objectives

Objective

Low-Distortion Signal Generation

- For analog/mixed signal IC Testing
- High quality test signal

Approach

- Rectangular add/subtract method
- Proposed phase control method

Digital ATE + Simple analog circuit & BOST



No need expensive signal generator

Outline

- **Research Background**
- **Signal Generation Method**
- **Phase Shift Technique**
- **Circuit Configuration & Simulation**
- **Conclusion**

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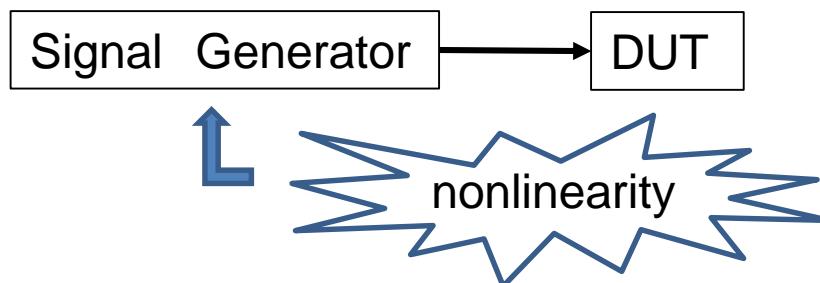
Research Background

- Testing analog ICs requires low distortion sinusoidal



Signal generator has nonlinearity

- Harmonic distortion caused
- Test accuracy deterioration



Objective

Low-Distortion Signal Generation at Low Cost

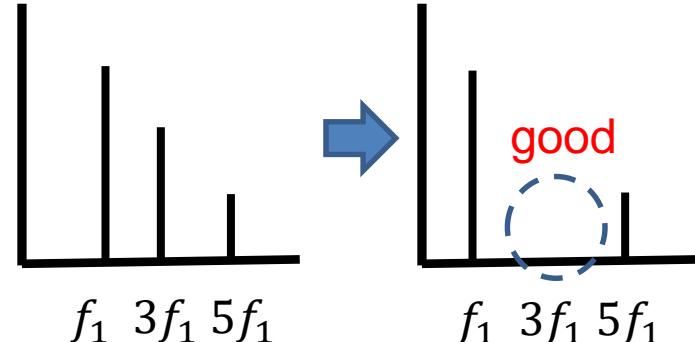
Problem of Our Previous Method

3rd harmonics suppression

Phase parameters

$$\varphi_1 = 2\pi \frac{\tau_1}{T}$$

3 rectangular add/subtract



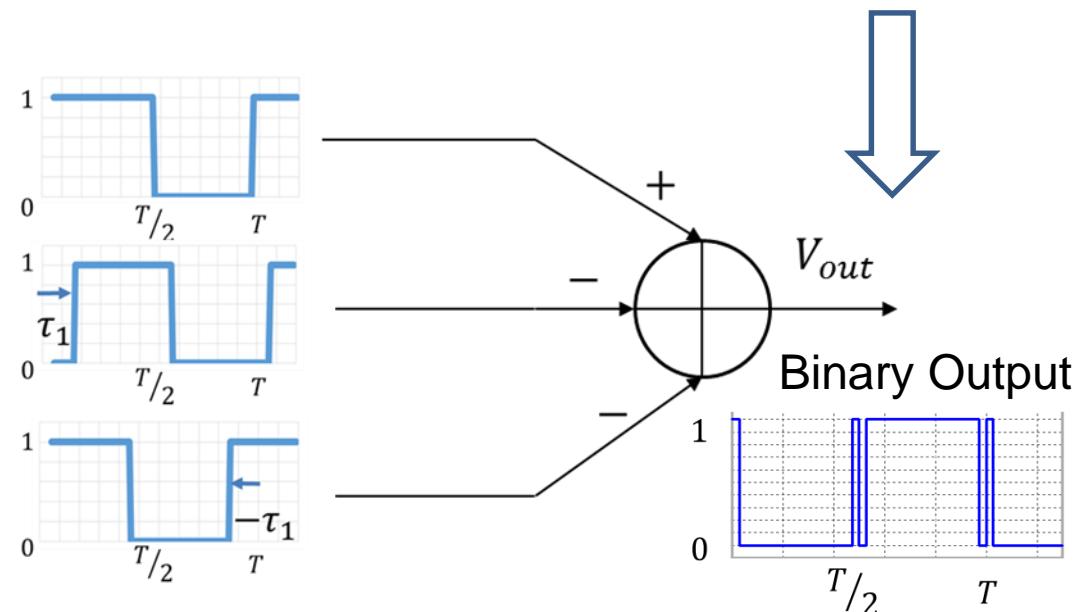
Phase shift parameter

$$\tau_1 = \pm \frac{T}{6k}$$

Phase shift parameter is simple

High resolution is not needed

Digital phase shift



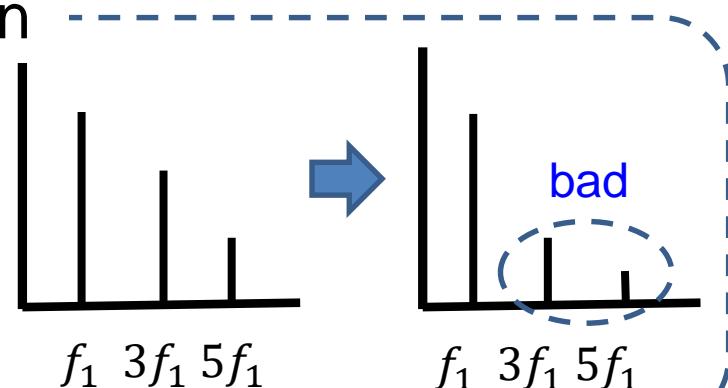
Problem of Conventional Method

3rd & 5th harmonics suppression

Phase parameters

$$\varphi_1 = 2\pi \frac{\tau_1}{T}, \varphi_2 = 2\pi \frac{\tau_2}{T}$$

5 rectangular add/subtract



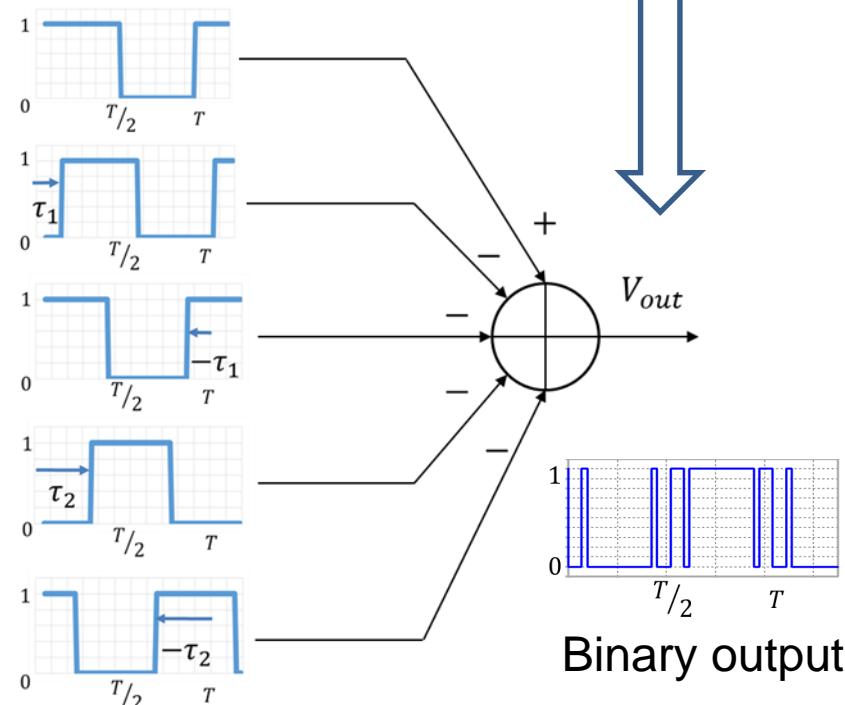
Phase shift parameter

$$\tau_1 = \frac{T}{2k\pi} \left(\cos^{-1} \left(\frac{1}{2} \left\{ 1 - 2 \cos \left(\frac{2k\pi}{T} \tau_2 \right) \right\} \right) \right)$$

Phase shift parameter is complex

High resolution is needed

Analog phase shift



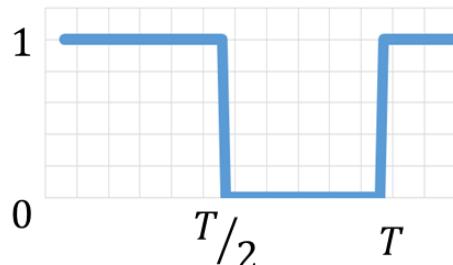
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Fourier Series Expansion

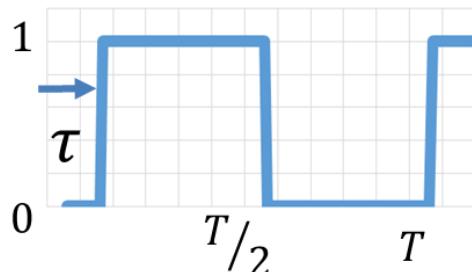
Duty 50% rectangular wave

$$f(t) = \begin{cases} 1 & \dots nT \leq t \leq (2n+1)T/2 \\ 0 & \dots (2n+1)T/2 < t \leq (n+1)T \end{cases} \quad (n = 0, 1, 2, \dots)$$

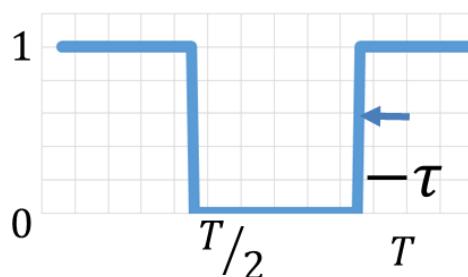


Fourier Series Expansion

$$f(t) = \frac{1}{2} + \sum_{m=1}^{\infty} \frac{2}{k\pi} \sin\left(\frac{2\pi}{T} kt\right) \quad (k = 2m - 1, m = 1, 2, \dots)$$



$$f(t - \tau) = \frac{1}{2} + \sum_{m=1}^{\infty} \frac{2}{k\pi} \sin\left\{\frac{2\pi}{T} k(t - \tau)\right\}$$



$$f(t + \tau) = \frac{1}{2} + \sum_{m=1}^{\infty} \frac{2}{k\pi} \sin\left\{\frac{2\pi}{T} k(t + \tau)\right\}$$

Single Harmonic Suppression Method

- Three rectangular waveforms add/subtract

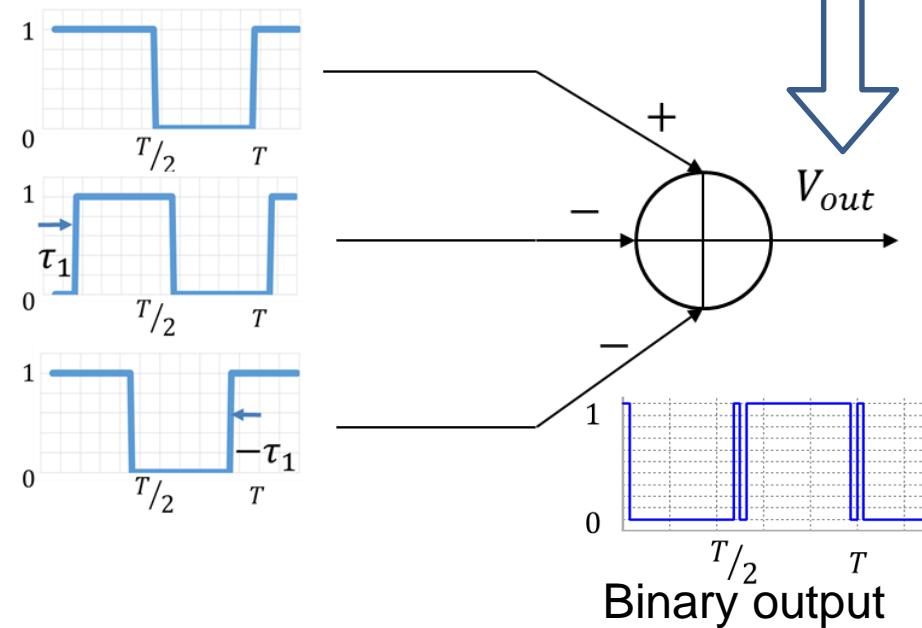
$$\begin{aligned}
 V_{out} &= f(t) - \{f(t - \tau_1) + f(t + \tau_1)\} \\
 &= -\frac{1}{2} + \sum_{m=1}^{\infty} \frac{2}{k\pi} \left\{ 1 - 2 \cos\left(\frac{2k\pi\tau_1}{T}\right) \right\} \sin\left(\frac{2k\pi}{T}t\right)
 \end{aligned}$$

(k = 2m - 1, m = 1, 2, ...)

- K-th HD suppression parameter

$$\frac{2}{k\pi} \left\{ 1 - 2 \cos\left(\frac{2k\pi\tau_1}{T}\right) \right\} \sin\left(\frac{2k\pi}{T}t\right) = 0$$

$$\tau_1 = \pm \frac{T}{6k}$$



Multiple Harmonics Suppression Method

- Five rectangular waveforms add/subtract

$$\begin{aligned}
 V_{out} &= f(t) - \{f(t - \tau_1) + f(t + \tau_1)\} - \{f(t - \tau_2) + f(t + \tau_2)\} \\
 &= -\frac{3}{2} + \sum_{m=1}^{\infty} \frac{2}{k\pi} \left\{ 1 - 2 \cos\left(\frac{2k\pi\tau_1}{T}\right) - 2 \cos\left(\frac{2k\pi\tau_2}{T}\right) \right\} \sin\left(\frac{2k\pi}{T}t\right)
 \end{aligned}$$

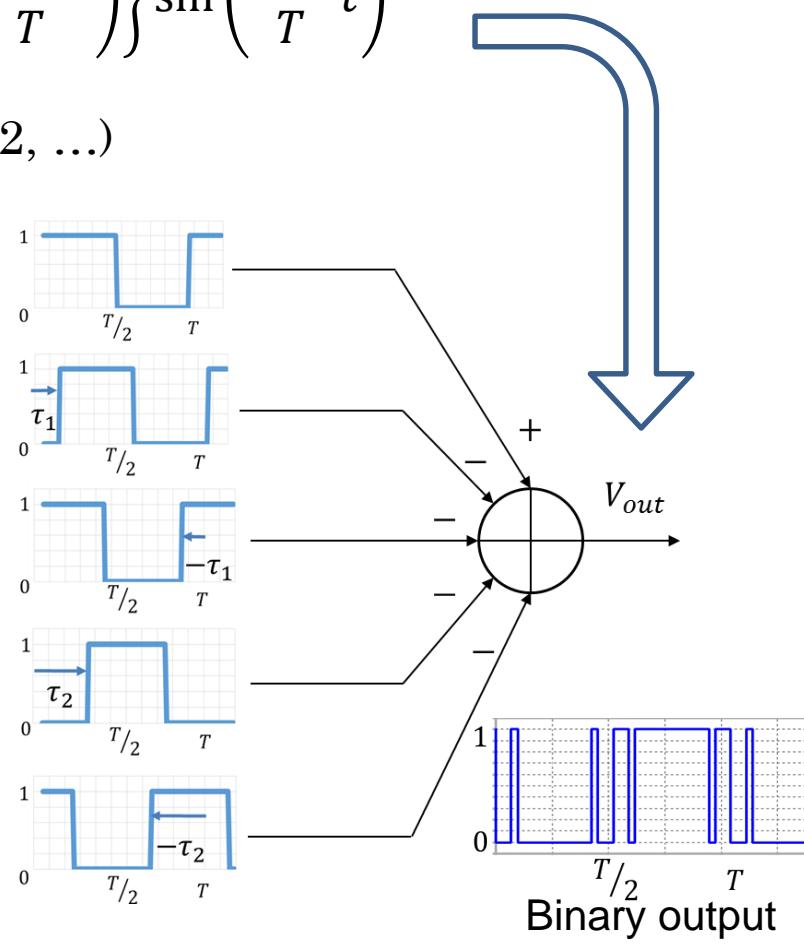
(k = 2m - 1, m = 1, 2, ...)

- K-th HD suppression parameter

$$\frac{2}{k\pi} \left\{ 1 - 2 \cos\left(\frac{2k\pi\tau_1}{T}\right) - 2 \cos\left(\frac{2k\pi\tau_2}{T}\right) \right\} \sin\left(\frac{2k\pi}{T}t\right) = 0$$



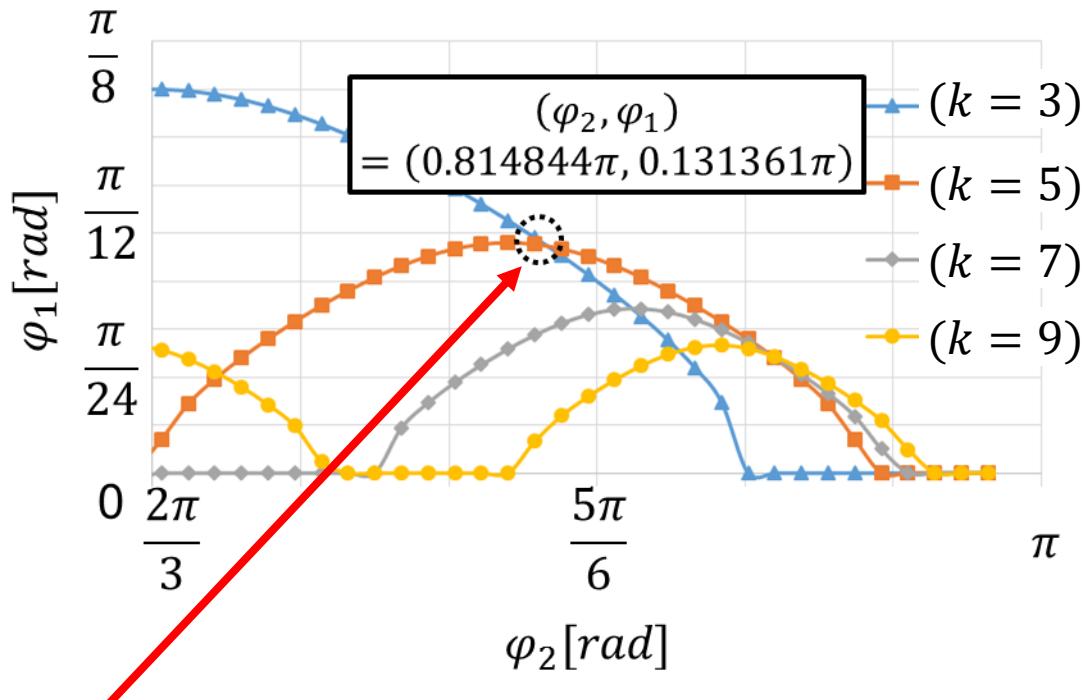
$$\tau_1 = \frac{T}{2k\pi} \left(\cos^{-1} \left(\frac{1}{2} \left\{ 1 - 2 \cos\left(\frac{2k\pi}{T}\tau_2\right) \right\} \right) \right)$$



Multiple Harmonics Suppression Parameter

$$\tau_1 = \frac{T}{2k\pi} \left(\cos^{-1} \left(\frac{1}{2} \left\{ 1 - 2 \cos \left(\frac{2k\pi}{T} \tau_2 \right) \right\} \right) \right)$$

$$\varphi = 2\pi \frac{\tau}{T} [rad]$$



Cross point \rightarrow multi harmonics suppression parameter

\rightarrow High quality needed

Outline

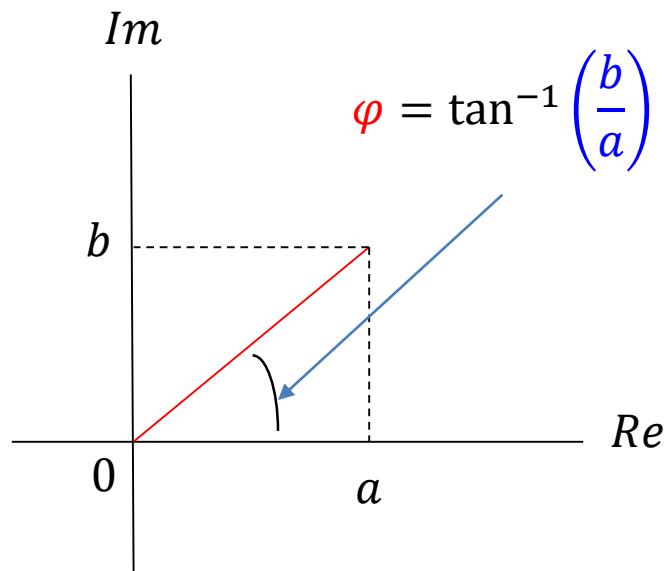
- Research Background
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Principle of Analog Phase Shift Technique

----- Formula of trigonometric function -----

$$a \sin(\omega t) + b \cos(\omega t) = \sqrt{a^2 + b^2} \sin(\omega t + \varphi)$$

$$\varphi = \tan^{-1} \left(\frac{b}{a} \right)$$



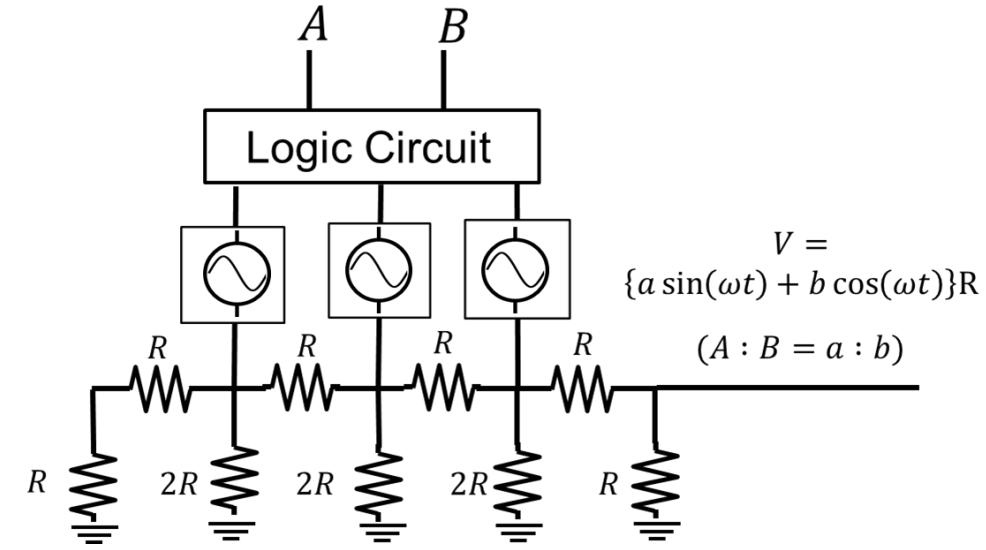
$$\varphi = \tan^{-1} \left(\frac{b}{a} \right)$$

Control amplitude ratio $\frac{b}{a}$

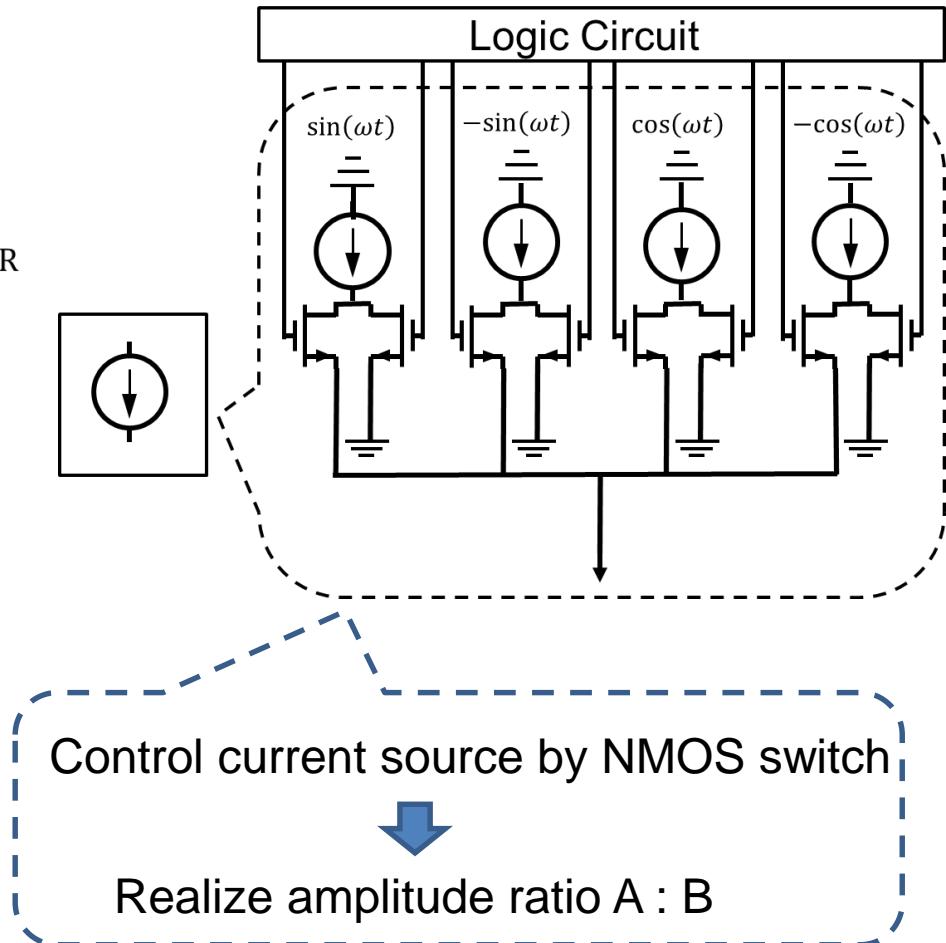


Control phase φ

Phase Control Circuit



R – 2R Ladder register
+
AC current source



Fractional Approximation Method

- Amplitude ratio $\frac{B}{A}$ of phase φ

$$\tan(20^\circ) = 0.363970 \dots \approx \frac{99}{273} = \frac{B}{A}$$

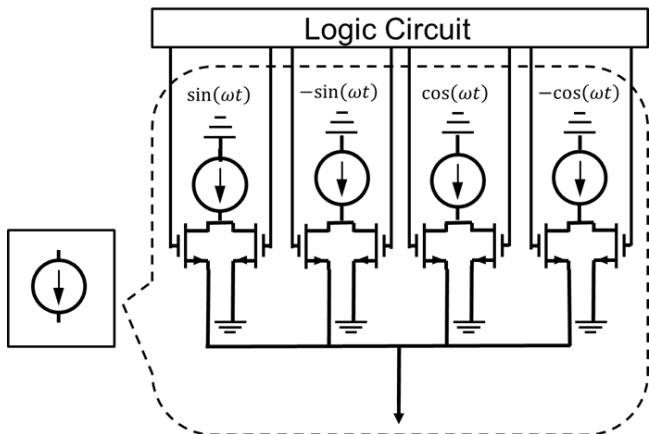
Fractional Approximation Method

$$3.14 \dots = 3 + \frac{1}{7.0625159} \approx 3 + \frac{1}{7} = \frac{22}{7}$$

$$3.14 \dots = 3 + \frac{1}{7 + \frac{1}{15.99593}} \approx 3 + \frac{1}{7 + \frac{1}{16}} = \frac{355}{113}$$

Using continued fraction  accurate amplitude ratio

Current Source Nonlinearity

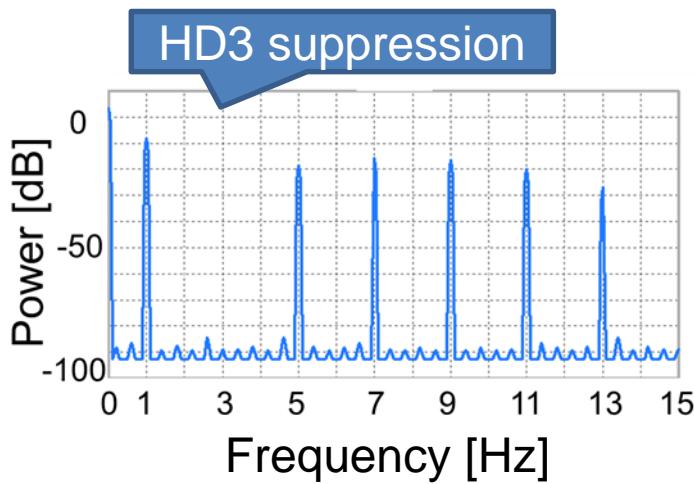


$$I = c_1 \sin \theta + c_3 \sin^3 \theta$$

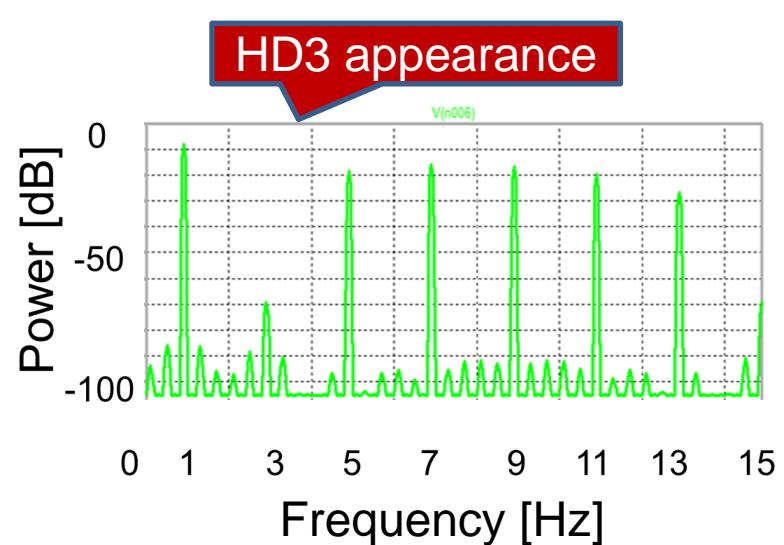
$$c_1 = 1, c_3 = -0.01$$

HD3 suppression case

linear



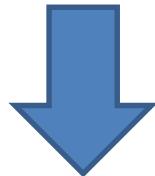
nonlinear



Amplitude Ratio Calculation

$$\begin{aligned}\frac{b}{a} &= -\frac{c_1 \sin(2\pi f_1 t + \theta) + c_3 \sin^3(2\pi f_1 t + \theta)}{c_1 \cos(2\pi f_1 t + \theta) + c_3 \cos^3(2\pi f_1 t + \theta)} \\ &= -\frac{c_1 + c_3 \sin^2(2\pi f_1 t + \theta)}{c_1 + c_3 \cos^2(2\pi f_1 t + \theta)} \tan(2\pi f_1 t + \theta)\end{aligned}$$

$$a_1 = 1, a_3 = -0.01, t = \frac{1}{9}[s], f_1 = 1[Hz], \theta = 0[^{\circ}]$$



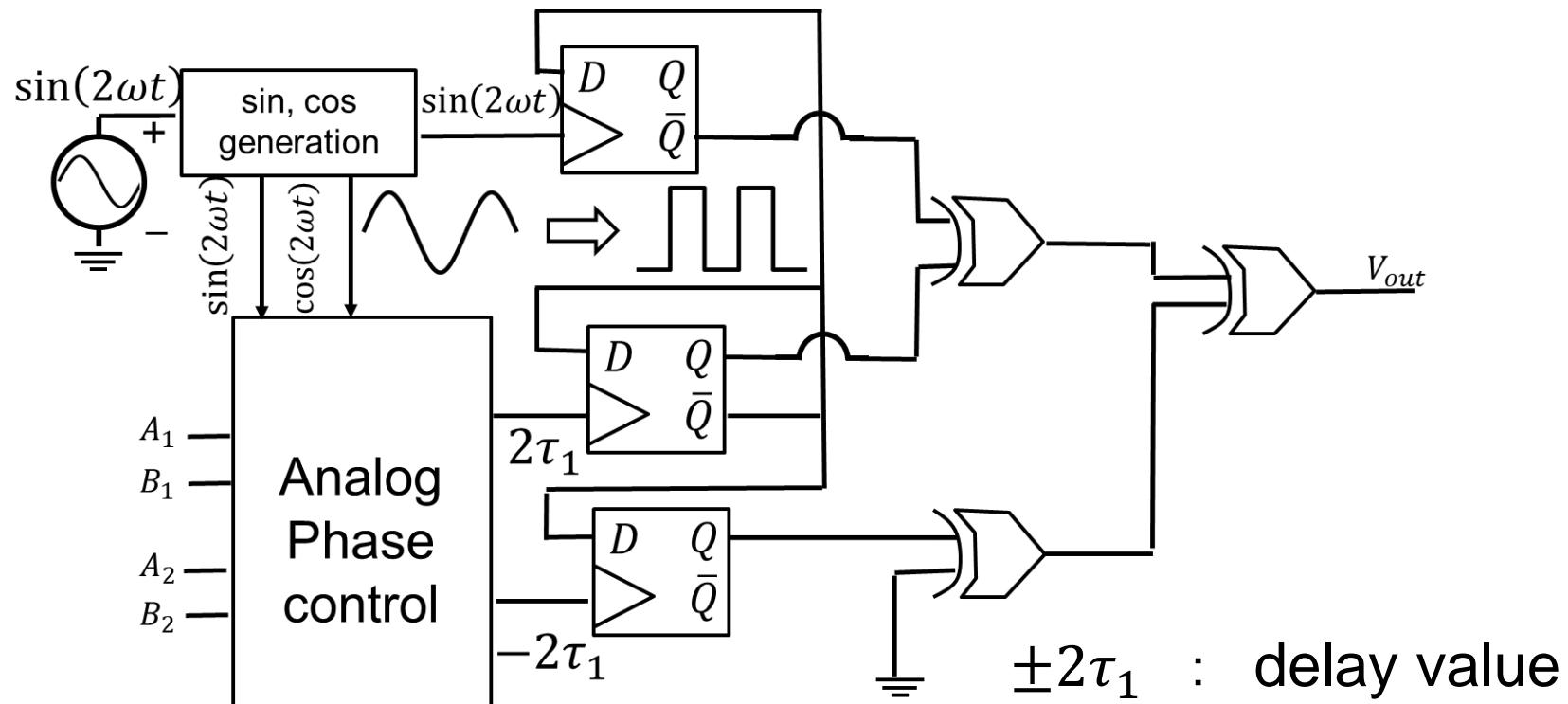
$$\frac{b}{a} = -\frac{1 - 0.01 \times \sin^2\left(\pm \frac{\pi}{9}\right)}{1 - 0.01 \times \cos^2\left(\pm \frac{\pi}{9}\right)} \tan\left(\pm \frac{\pi}{9}\right) = \mp 2.299560241 = \frac{\mp 522}{227}$$

Obtain appropriate amplitude ratio

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Duty50% Circuit Configuration



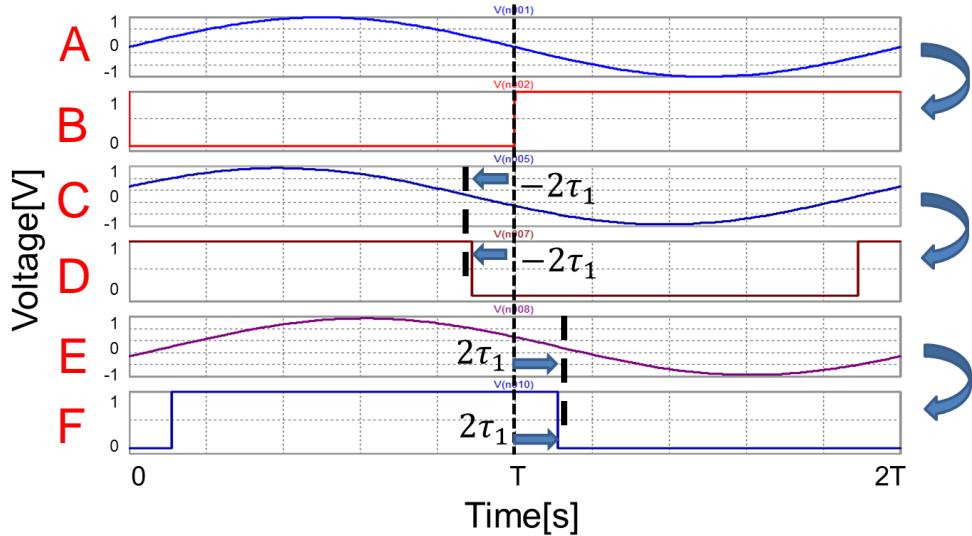
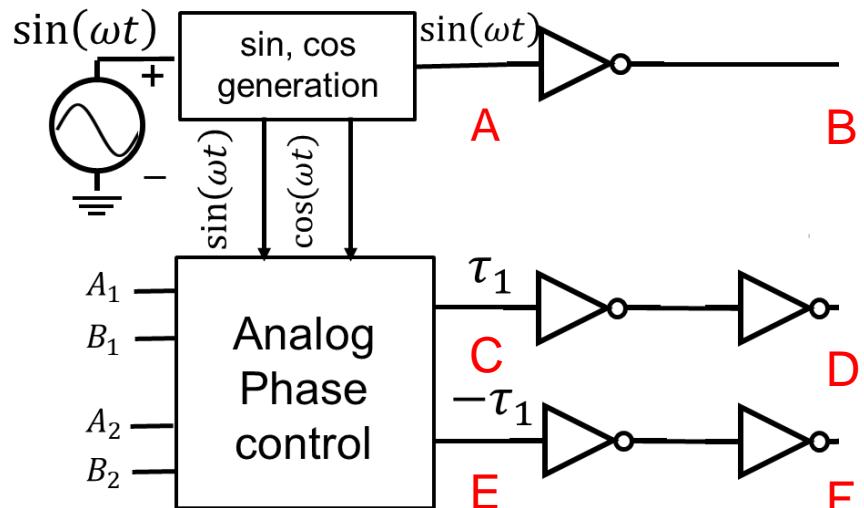
- Use a **frequency divider**
 - Guaranteed Duty 50%
 - Doubled phase and frequency
- Use **XOR** instead of opamp

From Sine to Rectangular Waveforms

```

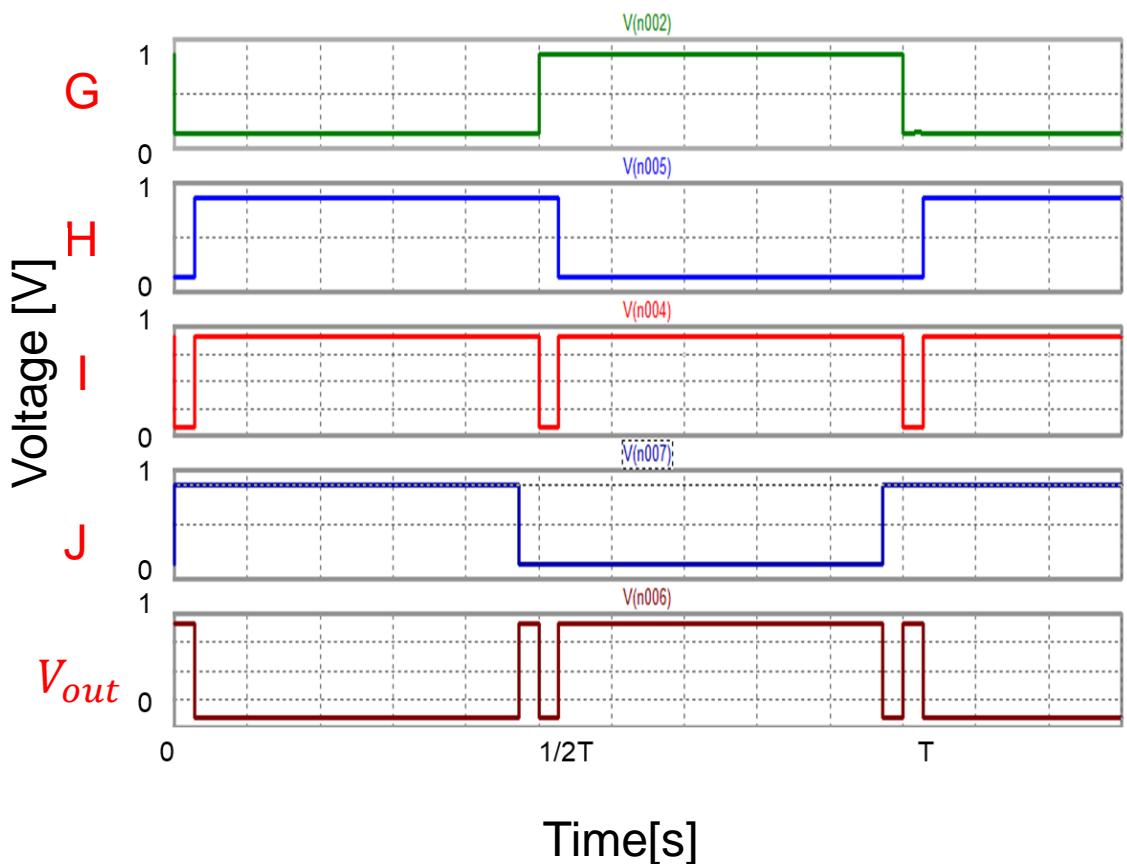
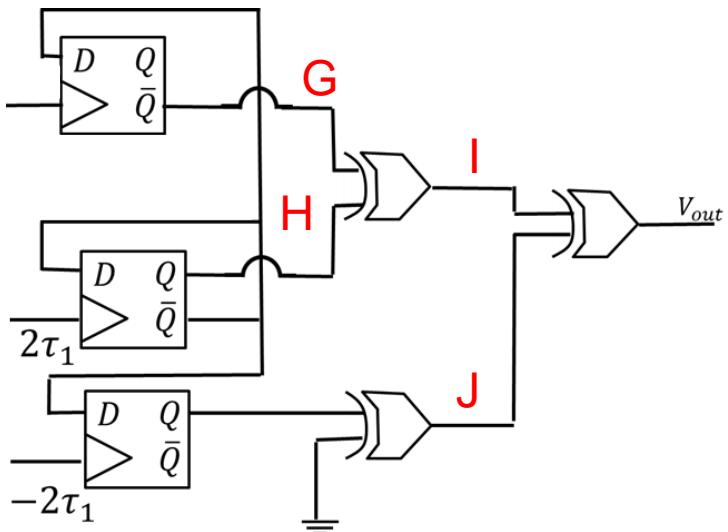
graph LR
    A[Sin wave] --> B[inverter]
    B --> C[rectangular wave]
    
```

The diagram illustrates a signal processing chain. It starts with a sine wave input, represented by the text "Sin wave" above a blue arrow pointing right. This arrow points to a block labeled "inverter". From the "inverter" block, another blue arrow points right to the output, which is labeled "rectangular wave" above the final blue arrow. Below the "Sin wave" input is the mathematical expression "Phase φ ". Below the "Binary change" output is the mathematical expression "Phase φ ".



XOR Behavior

Binary output \rightarrow Express with logic circuit

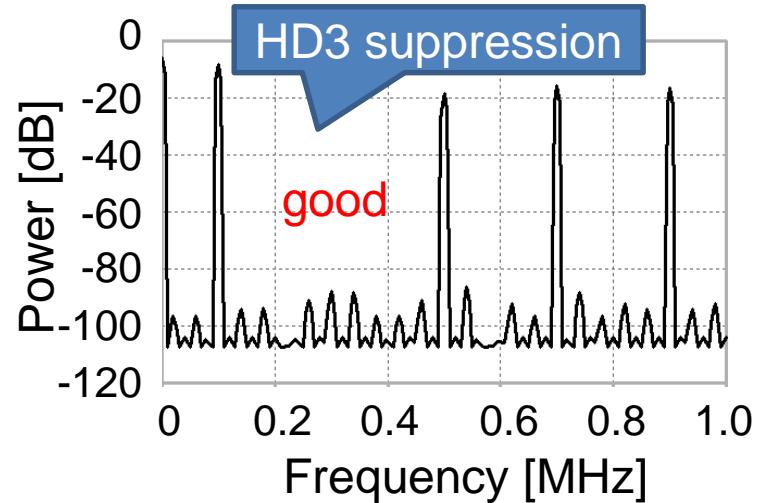
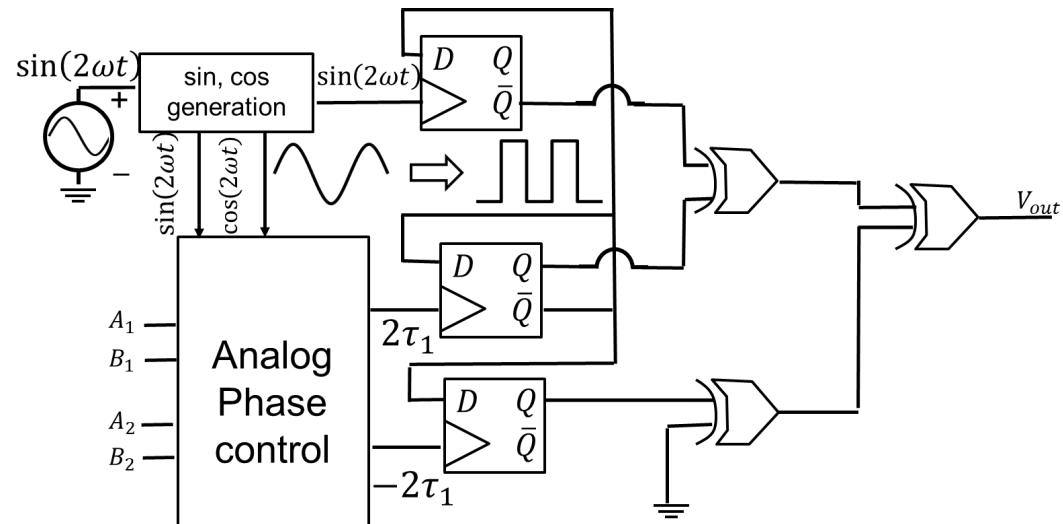


HD3 Suppression Simulation

Parameters

$$T/2 = 5 \text{ } [\mu\text{s}], c_1 = 1, c_2 = -0.1, c_3 = -0.01$$

$$2\tau_1 = \frac{10}{9} \text{ } [\mu\text{s}], \frac{b_1}{a_1} = \frac{587}{689}, \frac{b_2}{a_2} = \frac{350}{361}$$



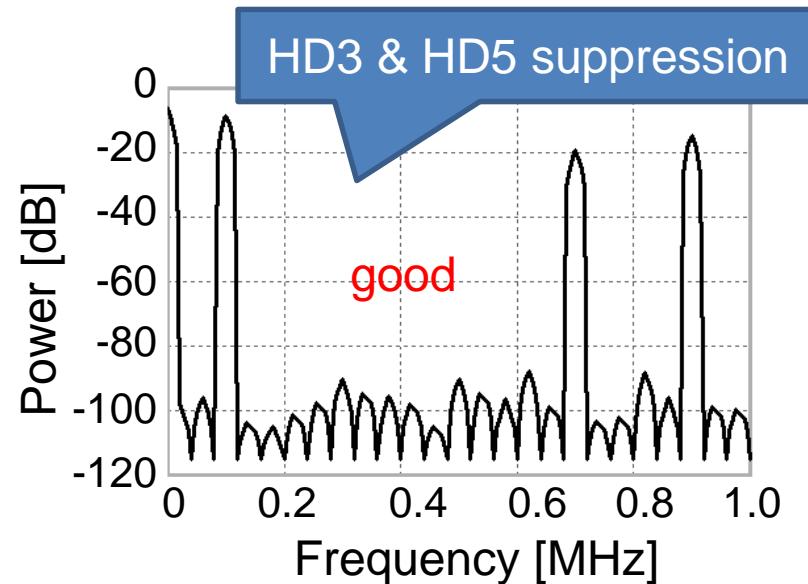
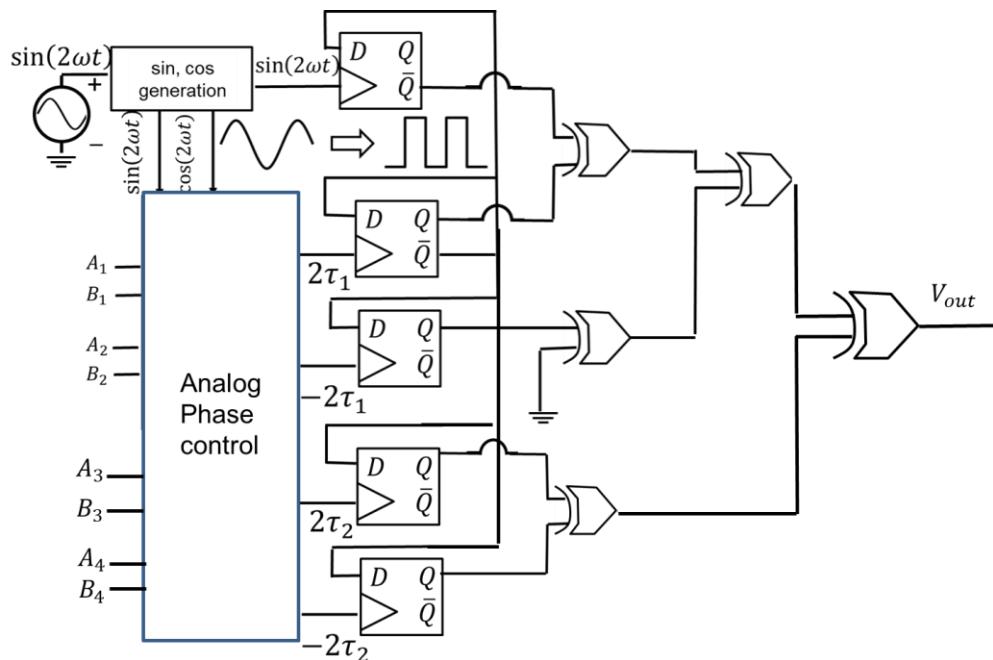
HD3 & HD5 Suppression Simulation

Parameters

$$T/2 = 5 \text{ } [\mu\text{s}], 2\tau_1 = 0.92578 \text{ } [\mu\text{s}], 2\tau_2 = 0.656805 \text{ } [\mu\text{s}]$$

$$c_1 = 1, c_2 = -0.1, c_3 = -0.05, c_4 = -0.01, c_5 = -0.005$$

$$\frac{b_1}{a_1} = \frac{489}{235}, \frac{b_2}{a_2} = \frac{313}{122}, \frac{b_3}{a_3} = \frac{938}{868}, \frac{b_4}{a_4} = \frac{929}{868}$$



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Conclusion

Summary

- We proposed low-distortion signal method using analog phase shift & rectangular.

Digital ATE + Simple analog circuit & BOST



No need expensive signal generator

Future task

- Consideration of delay time & threshold voltage of Flip-Flop
- It is necessary to verify with the actual circuit